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# Simultaneous Approximation of a Multivariate Function and its Derivatives by Multilinear Splines

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## Abstract

In this paper we consider the approximation of a function by its interpolating multilinear spline and the approximation of its derivatives by the derivatives of the corresponding spline. We derive formulas for the uniform approximation error on classes of functions with moduli of continuity bounded above by certain majorants.

*Keywords:* simultaneous approximation, multilinear splines, interpolation, modulus of continuity, approximation on a class, block partitions

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## 1. Basic definitions and notation

Let  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  be a point in Euclidean space  $\mathbb{R}^n$ . By  $C_D$  we denote the class of functions  $f(\mathbf{x}) = f(x_1, x_2, \dots, x_n)$  that are continuous on the domain  $D := [0, 1]^n \subset \mathbb{R}^n$ .

We consider a vector  $\mathbf{r} \in \{0, 1\}^n$ , i.e. a vector having  $n$  components each being either 0 or 1. Let  $C_D^{\mathbf{r}}$  be the class of functions,  $f(\mathbf{x}) \in C_D$ , with continuous derivatives

$$f^{(\mathbf{t})}(\mathbf{x}) = \frac{\partial^{\sum_{i=1}^n t_i} f}{\partial x^{t_1} \dots \partial x^{t_n}}(\mathbf{x}),$$

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where  $\mathbf{t} \in \{0, 1\}^n$  and  $t_i \leq r_i$  for each  $i = 1, \dots, n$ . We define  $f^{(0)}(\mathbf{x}) := f(\mathbf{x})$  and  $C_D^0 := C_D$ .

For any function  $f(\mathbf{x}) \in C_D$ , consistent with literature, we denote the uniform norm as

$$\|f\|_C := \max\{|f(\mathbf{x})| : \mathbf{x} \in D\}.$$

The next two definitions introduce two types of moduli of continuity of a given function  $f$ , both characterizing the smoothness of the original function  $f$ .

**Definition 1.** *If the function  $f(\mathbf{x})$  is bounded for  $x_i \in [a_i, b_i], i = 1, \dots, n$ , then its total modulus of continuity,  $\omega(f; \boldsymbol{\tau})$ , is defined as follows*

$$\begin{aligned} \omega(f; \boldsymbol{\tau}) &:= \omega(f; \mathbf{a}, \mathbf{b}; \boldsymbol{\tau}) \\ &= \sup \{|f(\mathbf{x}) - f(\mathbf{y})| : |x_i - y_i| \leq \tau_i; x_i, y_i \in [a_i, b_i]\}, \end{aligned}$$

where  $0 \leq \tau_i \leq b_i - a_i$ , for  $i = 1, \dots, n$  and  $\boldsymbol{\tau} := (\tau_1, \dots, \tau_n)$ ,  $\mathbf{a} := (a_1, \dots, a_n)$ ,  $\mathbf{b} := (b_1, \dots, b_n)$ .

In addition, we consider the following  $l_p$  distances,  $1 \leq p < \infty$ , between points  $\mathbf{x}, \mathbf{y} \in D \subset \mathbb{R}^n$ ,

$$\|\mathbf{x} - \mathbf{y}\|_p := \sqrt[p]{\sum_{i=1}^n |x_i - y_i|^p}.$$

**Definition 2.** *For the function  $f(\mathbf{x}) \in C_D$  and for given  $p$ ,  $1 \leq p < \infty$ , we define the modulus of continuity of function  $f$  with respect to  $p$  to be*

$$\omega_p(f; \gamma) := \sup \{|f(\mathbf{x}) - f(\mathbf{y})| : \mathbf{x}, \mathbf{y} \in D, \|\mathbf{x} - \mathbf{y}\|_p \leq \gamma\}, \quad 0 \leq \gamma \leq d_p,$$

where  $d_p := \max\{\|\mathbf{x} - \mathbf{y}\|_p : \mathbf{x}, \mathbf{y} \in D \subset \mathbb{R}^n\}$ .

We point out that

$$d_p = \sqrt[p]{n}.$$

Note that the moduli of continuity of all suitable functions have some common properties. We call all functions (univariate or multivariate) with these properties *functions of the moduli of continuity type* and use them to define classes of smoothness of functions.

**Definition 3.** Function  $\Omega(\boldsymbol{\tau})$  is called a function of modulus of continuity type, or MC-type function (for short), if the following properties hold for any vectors  $\boldsymbol{\gamma}, \boldsymbol{\tau} \in \mathbb{R}_+^n := \{\mathbf{x} \in \mathbb{R}^n : x_i \geq 0, i = 1, \dots, n\}$ :

1.  $\Omega(\mathbf{0}) = 0$ .
2.  $\Omega(\boldsymbol{\tau})$  is non-decreasing.
3.  $\Omega(\boldsymbol{\tau} + \boldsymbol{\gamma}) \leq \Omega(\boldsymbol{\tau}) + \Omega(\boldsymbol{\gamma})$ , that is  $\Omega(\boldsymbol{\tau})$  is subadditive.
4.  $\Omega(\boldsymbol{\tau})$  is continuous for all  $\tau_i, i = 1, \dots, n$ .

The following two definitions present the classes of functions that we will be working with in this paper.

**Definition 4.** Given an arbitrary  $n$ -variate MC-type function  $\Omega(\boldsymbol{\tau})$ , we define the class  $C_D^{\mathbf{r}}(\Omega)$ , where  $\mathbf{r} \in \{0, 1\}^n$  with  $C_D^{\mathbf{0}}(\Omega) := C_D(\Omega)$ , to be the class of functions  $f(\mathbf{x}) \in C_D^{\mathbf{r}}$ , such that the total modulus of continuity of their derivatives of order  $\mathbf{r}$  are bounded from above by the given  $\Omega(\boldsymbol{\tau})$

$$\omega(f^{(\mathbf{r})}; \boldsymbol{\tau}) \leq \Omega(\boldsymbol{\tau}), \quad 0 \leq \tau_i \leq 1, \quad i = 1, \dots, n. \quad (1)$$

**Definition 5.** Given an arbitrary univariate MC-type function  $\Omega(\gamma)$ , we define the class  $C_{D,p}^{\mathbf{r}}(\Omega)$ ,  $1 \leq p \leq \infty$ , where  $\mathbf{r} \in \{0, 1\}^n$  with  $C_{D,p}^{\mathbf{0}}(\Omega) := C_{D,p}(\Omega)$ , to be the class of functions  $f(\mathbf{x}) \in C_D^{\mathbf{r}}$ , such that their moduli of continuity are bounded from above by the given  $\Omega(\gamma)$

$$\omega_p(f^{(\mathbf{r})}; \gamma) \leq \Omega(\gamma), \quad 0 \leq \gamma \leq \sqrt[p]{n}. \quad (2)$$

## 2. Construction of the interpolating spline

In order to construct the interpolating spline for the given function  $f \in C_D$ , which will be the main approximation tool for  $f$  (and its derivatives will be used to approximate the derivatives of  $f$ ), we fix a vector  $\mathbf{m} = (m_1, \dots, m_n) \in \mathbb{N}^n$  and for each  $i = 1, \dots, n$  we first define the univariate grid of nodes as follows

$$\mathcal{D}_{m_i} = \left\{ 0, \frac{1}{m_i}, \dots, \frac{m_i - 1}{m_i}, 1 \right\}.$$

With the help of the standard Cartesian product we define the  $n$ -variate grid as

$$\mathcal{D}_{\mathbf{m}} = \mathcal{D}_{m_1} \times \dots \times \mathcal{D}_{m_n}.$$

Once the grid is constructed, each point on the grid is defined by a vector  $\mathbf{j} = (j_1, \dots, j_n)$  where  $j_i \in \{0, \dots, m_i\}$ , as follows

$$\mathbf{x}^{\mathbf{j}} := (x_1^{j_1}, \dots, x_n^{j_n}) := \left( \frac{j_1}{m_1}, \dots, \frac{j_n}{m_n} \right) \in \mathcal{D}_{\mathbf{m}}.$$

Having defined the grid, we next define the interpolating spline that will be used to approximate the given function and whose derivatives will be used to simultaneously approximate the derivatives of the function.

**Definition 6.** For the grid of nodes,  $\mathcal{D}_{\mathbf{m}}$ , and a given function  $f(\mathbf{x}) \in C_D$ , we define the multilinear ( $n$ -linear) interpolating spline,  $S_{\mathbf{m}}(f; \mathbf{x})$ , to satisfy the following conditions:

1. On every block  $D_{\mathbf{j}} := \prod_{i=1}^n [x_i^{j_i}, x_i^{j_i+1}]$ , where  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i - 1$ ,  $S_{\mathbf{m}}(f; \mathbf{x})$  is an algebraic polynomial of first degree in  $x_i$  for  $i = 1, \dots, n$ .
2.  $S_{\mathbf{m}}(f; \mathbf{x}^{\mathbf{j}}) = f(\mathbf{x}^{\mathbf{j}})$  for  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i$  and  $i = 1, \dots, n$ . In other words,  $S_{\mathbf{m}}(f; \mathbf{x})$  interpolates  $f(\mathbf{x})$  at the nodes  $\mathcal{D}_{\mathbf{m}}$ .

Note that for  $\mathbf{x} \in D_{\mathbf{j}}$ ,  $j_i = 0, \dots, m_i - 1$  and  $i = 1, \dots, n$ , the following holds

$$S_{\mathbf{m}}(f; \mathbf{x}) = \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left[ f(\mathbf{x}^{\mathbf{j}+\mathbf{l}}) \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \right], \quad (3)$$

where  $\mathbf{l} = (l_1, \dots, l_n)$  and

$$H_{0, j_i}(x_i) := m_i(x_i^{j_i+1} - x_i), \quad \sum_{l_i=0}^1 H_{l_i, j_i}(x_i) \equiv 1. \quad (4)$$

When taking the partial derivatives of  $S_{\mathbf{m}}(f; \mathbf{x})$ , there may be discontinuities at the points of the following set

$$A := \{\mathbf{x} : x_i^{j_i} \text{ is a component of } \mathbf{x} \text{ for some } i \text{ and some } j_i \in \{0, \dots, m_i\}\}.$$

The discontinuities of the partial derivatives of  $S_{\mathbf{m}}(f; \mathbf{x})$  may exist because  $S_{\mathbf{m}}(f; \mathbf{x})$  is a piecewise linear polynomial with respect to  $x_i$ , for  $i = 1, \dots, n$ . With these discontinuities all partial derivatives need to be defined carefully. In order to do so, we define the set  $M$  of indices as follows:

$$M := \{i : \text{The derivative of } S_{\mathbf{m}}(f; \mathbf{x}) \text{ is taken with respect to } x_i\}.$$

We use the notation  $|M|$  to denote the number of elements (cardinality) in set  $M$ .

Next, we introduce the functions  $F_M(\mathbf{x})$  and  $F_{M'}(\mathbf{x})$  - which will later be used to define the partial derivatives of  $S_{\mathbf{m}}(f; \mathbf{x})$  - as follows:

$$\begin{aligned} F_M(\mathbf{x}) &:= \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M} l_i} \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) f(\mathbf{x}^{\mathbf{j}+1}), \\ F_{M'}(\mathbf{x}) &:= \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M} l_i + 1} \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) f(\mathbf{x}^{\mathbf{j}+1}). \end{aligned}$$

**Remark.**  $F_M(\mathbf{x})$  is used if  $|M|$  is even, and  $F_{M'}(\mathbf{x})$  is used if  $|M|$  is odd. When stating the results, we will use  $M$  such that  $|M|$  is even, but the results also hold for  $M$  in the case when  $|M|$  is odd.

Let  $\mathbf{b} \in \{0, 1\}^n$ , where

$$b_i := \begin{cases} 1, & \text{if } i \in M \\ 0, & \text{if } i \notin M \end{cases},$$

then

$$S_{\mathbf{m}}^{(\mathbf{b})}(f; \mathbf{x}) = \left( \prod_{i \in M} m_i \right) F_M(\mathbf{x}), \quad (5)$$

for  $\mathbf{x} \in D'_{\mathbf{j}} := \prod_{i=1}^n I(x_i)$ , where

$$I(x_i) := \begin{cases} [x_i^{j_i}, x_i^{j_i+1}], & \text{if } j_i = 0, \dots, m_i - 2 \\ [x_i^{j_i}, x_i^{j_i+1}], & \text{if } j_i = m_i - 1 \end{cases}.$$

Finally, we introduce the errors of approximation for a given function (Definition 7) and error of approximation on a class of functions (Definition 8).

**Definition 7.** For given  $\mathbf{r} \in \{0, 1\}^n$  and a function  $f \in C_{\mathcal{D}}^{\mathbf{r}}$ , we denote the error of approximation of a function  $f^{(\mathbf{r})}(\mathbf{x})$  (or its derivative) by the interpolating spline  $S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x})$  (or its derivative, respectively) constructed above to be

$$\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x}) := |f^{(\mathbf{r})}(\mathbf{x}) - S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x})|, \quad \mathbf{x} \in D \quad (6)$$

with  $\mathcal{E}_{\mathbf{m}}^{\mathbf{0}}(f; \mathbf{x}) := \mathcal{E}_{\mathbf{m}}(f; \mathbf{x})$ .

**Definition 8.** For a given  $\mathbf{r} \in \{0, 1\}^n$  and for any class  $\mathcal{M} \in C_D^{\mathbf{r}}$ , we denote the error of approximation on the class  $\mathcal{M}$  by splines that interpolate at the nodes  $\mathcal{D}_{\mathbf{m}}$  to be

$$E_{\mathbf{m}}^{\mathbf{r}}(\mathcal{M}) := \sup \{ \|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f)\|_C : f \in \mathcal{M} \} \quad (7)$$

with  $E_{\mathbf{m}}^0(\mathcal{M}) := E_{\mathbf{m}}(\mathcal{M})$ .

In this paper, we present the explicit formulas for the uniform error of approximation of multivariate functions from some classes of smoothness by multilinear interpolating splines as well as the error of approximation of the derivatives of functions from the considered class by the derivatives of the corresponding splines. An analogous univariate result for approximating the function from the same class is contained in [1], and the result for approximating the derivatives is contained in [2]. In the case of bivariate functions from the class  $C_D^{\mathbf{r}}(\Omega)$ , earlier known results for such functions are in the paper of Storchai [3] and for the derivatives are in works of Vakarchuk and Shabozov [4, 5]. For the class  $C_{D,p}^{\mathbf{r}}(\Omega)$  the known results are only for the cases  $p = 1$  [6] and  $p = 2$  [7] for functions and [6, 5] for derivatives, respectively. We have extended their results to the case of arbitrary dimension and arbitrary  $1 \leq p \leq 3$ .

### 3. The error of approximation on classes $C_D(\Omega)$ and $C_{D,p}(\Omega)$

In this section, we estimate the error of approximation by interpolating splines on the classes  $C_D(\Omega)$  and  $C_{D,p}(\Omega)$  defined in Definitions 4 and 5.

**Theorem 1.** Let  $\Omega(\boldsymbol{\tau})$  be an arbitrary concave (in each variable) MC-type function. Then for  $\mathbf{m} \in \mathbb{N}^n$  with  $m_i \geq 2$  for  $i = 1, \dots, n$ , the error on the class  $C_D(\Omega)$  is

$$E_{\mathbf{m}}(C_D(\Omega)) = \Omega\left(\frac{1}{2\mathbf{m}}\right).$$

#### Proof

Let an arbitrary function  $f \in C_D(\Omega)$  be given. Without loss of generality we consider  $\mathbf{x} \in D_{\mathbf{j}} = \prod_{i=1}^n [x_i^{j_i}, x_i^{j_i+1}]$  for some  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i \in \{0, \dots, m_i - 1\}$ . By Definition 7, using connection (4), we have

$$\begin{aligned} \mathcal{E}_{\mathbf{m}}(f; \mathbf{x}) &= |f(\mathbf{x}) - S_{\mathbf{m}}(f; \mathbf{x})| \\ &= \left| \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) (f(\mathbf{x}) - f(\mathbf{x}^{\mathbf{j}+1})) \right|, \end{aligned}$$

where  $\mathbf{x}^{\mathbf{j}+1} = (x_1^{j_1+1}, \dots, x_n^{j_n+1})$  and  $\mathbf{l} = (l_1, \dots, l_n) \in \{0, 1\}^n$  for  $i = 1, \dots, n$ .

Using the triangle inequality, Definition 1, and Definition 4, we obtain

$$\begin{aligned} |\mathcal{E}_{\mathbf{m}}(f; \mathbf{x})| &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) |f(\mathbf{x}) - f(\mathbf{x}^{\mathbf{j}+1})| \\ &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \omega(f; |\mathbf{x} - \mathbf{x}^{\mathbf{j}+1}|) \\ &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \Omega(|\mathbf{x} - \mathbf{x}^{\mathbf{j}+1}|), \end{aligned}$$

where  $|\mathbf{x} - \mathbf{x}^{\mathbf{j}+1}| = (|x_1 - x_1^{j_1+1}|, \dots, |x_n - x_n^{j_n+1}|)$ .

Since  $\mathbf{x} \in D_j$  and function  $\Omega(\boldsymbol{\tau})$  is concave in each variable, we have

$$|\mathcal{E}_{\mathbf{m}}(f; \mathbf{x})| \leq \Omega(\lambda(x_1), \dots, \lambda(x_n)),$$

where

$$\lambda(x_i) := H_{0, j_i}(x_i)(x_i - x_i^{j_i}) + H_{1, j_i}(x_i)(x_i^{j_i+1} - x_i), \quad i = 1, \dots, n. \quad (8)$$

Since the function of MC-type is non-decreasing, we need to find  $\max\{\lambda(x_i) : x_i \in [x_i^{j_i}, x_i^{j_i+1}]\}$  for  $i = 1, \dots, n$ . For convenience, we use the substitution  $x_i = t$ :

$$\begin{aligned} \lambda(t) &= H_{0, j_i}(t)(t - x_i^{j_i}) + H_{1, j_i}(t)(x_i^{j_i+1} - t) \\ &= (m_i x_i^{j_i+1} - m_i t)(t - x_i^{j_i}) + (1 - m_i x_i^{j_i+1} + m_i t)(x_i^{j_i+1} - t) \\ &= 3m_i x_i^{j_i+1} t - 2m_i t^2 + m_i x_i^{j_i} t - m_i x_i^{j_i} x_i^{j_i+1} - m_i (x_i^{j_i+1})^2 + x_i^{j_i+1} - t. \end{aligned}$$

Thus, taking the derivative of  $\lambda(t)$  with respect to  $t$ , setting  $\lambda'(t) = 0$ , and solving for  $t$  yields

$$t = \frac{x_i^{j_i} + x_i^{j_i+1}}{2}, \quad \text{and hence} \quad \lambda\left(\frac{x_i^{j_i} + x_i^{j_i+1}}{2}\right) = \frac{1}{2m_i}.$$

In order to show that  $\frac{1}{2m_i}$  is a maximum, we take second derivative

$$\lambda''(t) = -4m_i.$$



Since  $m_i \geq 2$ , we have  $\lambda''(t) < 0$ . Hence,  $\frac{1}{2m_i}$  is a maximum and we obtain

$$\max\{\lambda(x_i) : x_i \in [x_i^{j_i}, x_i^{j_i+1}]\} = \lambda\left(\frac{x_i^{j_i} + x_i^{j_i+1}}{2}\right) = \frac{1}{2m_i}, \quad i = 1, \dots, n. \quad (9)$$

As  $\Omega(\boldsymbol{\tau})$  is non-decreasing, we conclude

$$|\mathcal{E}_{\mathbf{m}}(f; x)| \leq \Omega\left(\frac{1}{2\mathbf{m}}\right).$$

Since last inequality holds for any  $f \in C_D(\Omega)$ , we have

$$E_{\mathbf{m}}(C_D(\Omega)) \leq \Omega\left(\frac{1}{2\mathbf{m}}\right). \quad (10)$$

Next, we present a particular function from  $C_D(\Omega)$  (called an *extremal function*) for which (10) occurs with equality. We define the extremal function  $f_0$  as follows

$$f_0(\mathbf{x}) := \Omega\left(\min\{x_1 - x_1^{j_1}, x_1^{j_1+1} - x_1\}, \dots, \min\{x_n - x_n^{j_n}, x_n^{j_n+1} - x_n\}\right),$$

where  $\mathbf{x} = (x_1, \dots, x_n) \in D_{\mathbf{j}}$  for fixed  $\mathbf{j}$  and  $f_0(\mathbf{x}) = 0$  for  $\mathbf{x} \notin D_{\mathbf{j}}$ . Then we have  $f_0 \in C_D(\Omega)$ , and  $f_0(\mathbf{x}^{\mathbf{j}}) = 0$  for  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i$  and  $i = 1, \dots, n$ . In addition, we have

$$\|\mathcal{E}_{\mathbf{m}}(f_0)\|_C = \|f_0\|_C,$$

since  $S_{\mathbf{m}}(f_0; \mathbf{x})$  is linear on each partition element and interpolates  $f_0(\mathbf{x})$  at the nodes of  $\mathcal{D}_{\mathbf{m}}$ . Consequently, the following estimates hold:

$$E_{\mathbf{m}}(C_D(\Omega)) \geq \|\mathcal{E}_{\mathbf{m}}(f_0)\|_C = \|f_0\|_C \geq f_0\left(\frac{1}{2\mathbf{m}}\right) = \Omega\left(\frac{1}{2\mathbf{m}}\right). \quad (11)$$

Combining (10) and (11), we obtain

$$E_{\mathbf{m}}(C_D(\Omega)) = \Omega\left(\frac{1}{2\mathbf{m}}\right). \quad \square$$

Theorem 2 gives the error  $E_{\mathbf{m}}(C_{D,p}(\Omega))$  for  $1 \leq p \leq 3$ , where  $C_{D,p}(\Omega)$  is defined in (2).

**Theorem 2.** Let  $\Omega(\gamma)$  be an arbitrary concave, MC-type, univariate function. Then for  $\mathbf{m} \in \mathbb{N}^n$  with  $m_i \geq 2$  for all  $i = 0, \dots, n$ , the error on the class  $C_{D,p}(\Omega)$  for  $1 \leq p \leq 3$  is

$$E_{\mathbf{m}}(C_{D,p}(\Omega)) = \Omega \left( \frac{1}{2} \sqrt[p]{\sum_{i=1}^n \frac{1}{m_i^p}} \right).$$

**Proof**

For any  $\mathbf{x}$  from an arbitrary  $D_{\mathbf{j}} := \prod_{i=1}^n [x_i^{j_i}, x_i^{j_i+1}]$  and for an arbitrary  $f \in C_{D,p}(\Omega)$  by Definition 7, we have

$$\begin{aligned} \mathcal{E}_{\mathbf{m}}(f; \mathbf{x}) &= |f(\mathbf{x}) - S_{\mathbf{m}}(f; \mathbf{x})| \\ &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) |f(\mathbf{x}) - f(\mathbf{x}^{\mathbf{j}+1})|, \end{aligned}$$

where  $\mathbf{x}^{\mathbf{j}+1} = (x_1^{j_1+1}, \dots, x_n^{j_n+1})$  and  $j_i = 0, \dots, m_i - 1$ ,  $\mathbf{l} = (l_1, \dots, l_n) \in \{0, 1\}^n$  for  $i = 1, \dots, n$ .

Using Definition 2, we have

$$\mathcal{E}_{\mathbf{m}}(f; \mathbf{x}) \leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \omega_p \left( \sqrt[p]{\sum_{i=1}^n |x_i - x_i^{j_i+l_i}|^p} \right).$$

Using Definition 5 for the class  $C_{D,p}(\Omega)$ , relation (4), and the fact that  $\Omega(\gamma)$  and function  $t^{\frac{1}{p}}$ ,  $1 \leq p \leq 3$ , are both concave functions, we obtain

$$\begin{aligned} \mathcal{E}_{\mathbf{m}}(f; \mathbf{x}) &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \Omega \left( \sqrt[p]{\sum_{i=1}^n |x_i - x_i^{j_i+l_i}|^p} \right) \\ &\leq \Omega \left( \sqrt[p]{\sum_{i=1}^n \left[ \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) |x_i - x_i^{j_i+l_i}|^p \right]} \right) \\ &= \Omega \left( \sqrt[p]{\sum_{i=1}^n \left[ \left( \sum_{l_i=0}^1 H_{l_i, j_i}(x_i) |x_i - x_i^{j_i+l_i}|^p \right) \left( \prod_{k=1; k \neq i}^n \left[ \sum_{l_k=0}^1 H_{l_k, j_k}(x_k) \right] \right) \right]} \right) \\ &= \Omega \left( \sqrt[p]{\sum_{i=1}^n \left[ \sum_{l_i=0}^1 H_{l_i, j_i}(x_i) |x_i - x_i^{j_i+l_i}|^p \right]} \right). \end{aligned}$$

For  $i = 1, \dots, n$ , we denote

$$\begin{aligned}\alpha(x_i) &:= \sum_{l_i=0}^1 H_{l_i, j_i}(x_i) |x_i - x_i^{j_i+l_i}|^p \\ &= H_{0, j_i}(x_i)(x_i - x_i^{j_i})^p + H_{1, j_i}(x_i)(x_i^{j_i+1} - x_i)^p.\end{aligned}\quad (12)$$

We have

$$\begin{aligned}\alpha(x_i) &:= H_{0, l_i}(x_i)(x_i - x_i^{j_i})^p + H_{1, l_i}(x_i)(x_i^{j_i+1} - x_i)^p \\ &= m_i(x_i^{j_i+1} - x_i)(x_i - x_i^{j_i})^p + m_i\left(\frac{1}{m_i} - x_i^{j_i+1} + x_i\right)(x_i^{j_i+1} - x_i)^p \\ &= m_i(x_i^{j_i+1} - x_i)(x_i - x_i^{j_i})^p + m_i(x_i - x_i^{j_i})(x_i^{j_i+1} - x_i)^p \\ &= m_i(x_i^{j_i+1} - x_i)^{p+1} \left( \left( \frac{x_i - x_i^{j_i}}{x_i^{j_i+1} - x_i} \right)^p + \frac{x_i - x_i^{j_i}}{x_i^{j_i+1} - x_i} \right)\end{aligned}$$

Using the following inequality [8, p. 334]

$$2^p(t^p + t) \leq (1+t)^{p+1}, \quad t \geq 0, \quad 0 < p \leq 3$$

for  $t = \frac{x_i - x_i^{j_i}}{x_i^{j_i+1} - x_i}$  and  $1 \leq p \leq 3$ , we have

$$\begin{aligned}\alpha(x_i) &\leq \frac{m_i}{2^p}(x_i^{j_i+1} - x_i)^{p+1} \left( 1 + \frac{x_i - x_i^{j_i}}{x_i^{j_i+1} - x_i} \right)^{p+1} \\ &= \frac{m_i}{2^p}(x_i^{j_i+1} - x_i)^{p+1} = \frac{m_i}{2^p} \left( \frac{1}{m_i} \right)^{p+1} = \frac{1}{(2m_i)^p}.\end{aligned}$$

Since  $\Omega(\gamma)$  is non-decreasing, we obtain

$$\mathcal{E}_{\mathbf{m}}(f, \mathbf{x}) \leq \Omega \left( \sqrt[p]{\sum_{i=1}^n \frac{1}{(2m_i)^p}} \right) = \Omega \left( \frac{1}{2} \sqrt[p]{\sum_{i=1}^n \frac{1}{(m_i)^p}} \right).$$

Since last inequality holds for any  $f \in C_{D,p}(\Omega)$ , we have

$$E_{\mathbf{m}}(C_{D,p}(\Omega)) \leq \Omega \left( \frac{1}{2} \sqrt[p]{\sum_{i=1}^n \frac{1}{(m_i)^p}} \right). \quad (13)$$

Finally, we consider an extremal function  $f_0$ , defined as follows

$$f_0(\mathbf{x}) := \Omega \left( \sqrt[p]{\sum_{i=1}^n (\min\{x_i - x_i^{j_i}, x_i^{j_i+1} - x_i\})^p} \right),$$

where  $\mathbf{x} \in D_{\mathbf{j}}$  and  $f_0(\mathbf{x}) = 0$  for  $\mathbf{x} \notin D_{\mathbf{j}}$ . From the way  $f_0$  is defined, it is easy to see that  $f_0 \in C_{D,p}(\Omega)$ . Note that  $f_0(\mathbf{x}^{\mathbf{j}}) = 0$  for  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i$ ,  $i = 1, \dots, n$ . This, along with the linearity of  $S_{\mathbf{m}}(f, \mathbf{x})$  on each element of the partition, implies that  $S_{\mathbf{m}}(f, \mathbf{x}) = 0$  and

$$\|\mathcal{E}_{\mathbf{m}}(f_0)\|_C = \|f_0\|_C. \quad (14)$$

Using (14), we obtain

$$E_{\mathbf{m}}(C_{D,p}(\Omega)) \geq \|\mathcal{E}_{\mathbf{m}}(f_0)\|_C = \|f_0\|_C \geq f_0 \left( \frac{1}{2\mathbf{m}} \right) = \Omega \left( \frac{1}{2} \sqrt[p]{\sum_{i=1}^n \frac{1}{m_i^p}} \right). \quad (15)$$

Combining (13) and (15), we have

$$E_{\mathbf{m}}(C_{D,p}(\Omega)) = \Omega \left( \frac{1}{2} \sqrt[p]{\sum_{i=1}^n \frac{1}{m_i^p}} \right). \quad \square$$

#### 4. Divided differences

In order to state the remaining results of this paper, we need to recall the definitions and some properties of divided differences.

Given function  $f$ , we define

$$\delta(f; \mathbf{x}, \mathbf{y}) := \frac{f(\mathbf{x}) - f(\mathbf{y})}{\prod_{i \in G} (x_i - y_i)}, \quad \mathbf{x}, \mathbf{y} \in \mathbb{R}^n, \quad (16)$$

where  $G = \{i \in \{1, \dots, n\} : x_i \neq y_i\}$ .

We remind the reader that for given  $\mathbf{r} \in \{0, 1\}^n$ , the set  $M$  is defined as  $M = \{i : r_i = 1\}$ . In the remaining sections we will express  $S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x})$

in terms of the divided difference of the function  $f$  for the terms  $x_i$ , where  $i \in M$ . Recall that from (5) we have

$$\begin{aligned} S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x}) &= \left( \prod_{i \in M} m_i \right) F_M(\mathbf{x}) \\ &= \left( \prod_{i \in M} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M} l_i} \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) f(\mathbf{x}^{\mathbf{j}+1}), \end{aligned}$$

where  $\mathbf{x}^{\mathbf{j}+1} = (x_1^{j_1+1}, \dots, x_n^{j_n+1})$  and  $j_i = 0, \dots, m_i - 1$ ,  $\mathbf{l} = (l_1, \dots, l_n) \in \{0, 1\}^n$  for  $i = 1, \dots, n$ . Fixing point  $x_a$  such that  $a \in M$ , we have

$$\begin{aligned} S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x}) &= m_a \left( \prod_{i \in M; i \neq a} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_{a-1}=0}^1 \sum_{l_{a+1}=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M; i \neq a} l_i} \\ &\quad \times \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) f(x_1^{j_1+1}, \dots, x_a^{j_a}, \dots, x_n^{j_n+1}) \\ &+ m_a \left( \prod_{i \in M; i \neq a} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_{a-1}=0}^1 \sum_{l_{a+1}=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M; i \neq a} l_i+1} \\ &\quad \times \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) f(x_1^{j_1+1}, \dots, x_a^{j_a+1}, \dots, x_n^{j_n+1}) \\ &= m_a \left( \prod_{i \in M; i \neq a} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_{a-1}=0}^1 \sum_{l_{a+1}=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M; i \neq a} l_i+1} \\ &\quad \times \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) \left[ f(x_1^{j_1+1}, \dots, x_a^{j_a+1}, \dots, x_n^{j_n+1}) \right. \\ &\quad \left. - f(x_1^{j_1+1}, \dots, x_a^{j_a}, \dots, x_n^{j_n+1}) \pm f(x_1^{j_1+1}, \dots, x_a, \dots, x_n^{j_n+1}) \right]. \end{aligned}$$

Setting

$$\begin{aligned} \mathbf{v} &= (x_1^{j_1+1}, \dots, x_a^{j_a-l_a+1}, \dots, x_n^{j_n+1}) \\ \mathbf{w} &= (x_1^{j_1+1}, \dots, x_a^{j_a}, \dots, x_n^{j_n+1}) \\ \mathbf{y} &= (x_1^{j_1+1}, \dots, x_a^{j_a+1}, \dots, x_n^{j_n+1}) \\ \mathbf{z} &= (x_1^{j_1+1}, \dots, x_a, \dots, x_n^{j_n+1}) \end{aligned}$$

and using the divided difference defined in (16), we have

$$\begin{aligned}
& S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x}) \\
&= m_a \left( \prod_{i \in M; i \neq a} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_{a-1}=0}^1 \sum_{l_{a+1}=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M; i \neq a} l_i + 1} \\
&\quad \times \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) [(x_a^{j_a+1} - x_a) \delta(f; \mathbf{y}, \mathbf{z}) + (x_a - x_{a, j_a}) \delta(f; \mathbf{z}, \mathbf{w})] \\
&= \left( \prod_{i \in M; i \neq a} m_i \right) \sum_{l_1=0}^1 \sum_{l_2=0}^1 \dots \sum_{l_n=0}^1 (-1)^{\sum_{i \in M; i \neq a} l_i + 1} H_{l_a, j_a}(x_a) \\
&\quad \times \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) \delta(f; \mathbf{v}, \mathbf{z}).
\end{aligned}$$

Repeating this process for each  $i \in M$  and using the fact that  $|M|$  is even, we eventually obtain that the sign of each term is positive. We define the vectors  $\mathbf{q}, \mathbf{p} \in D_j$  as follows

$$\begin{aligned}
\mathbf{q} &= (q_1, q_2, \dots, q_n) : q_i = \begin{cases} x_i^{j_i - l_i + 1}, & \text{if } i \in M \\ x_i^{j_i + l_i}, & \text{if } i \notin M \end{cases} \\
\mathbf{p} &= (p_1, p_2, \dots, p_n) : p_i = \begin{cases} x_i, & \text{if } i \in M \\ x_i^{j_i + l_i}, & \text{if } i \notin M \end{cases}.
\end{aligned}$$

Therefore, we obtain

$$S_{\mathbf{m}}^{(\mathbf{r})}(f; \mathbf{x}) = \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \delta(f; \mathbf{q}, \mathbf{p}).$$

Combining it with (5) and using the triangle inequality, we obtain

$$\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x}) \leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) |f^{(\mathbf{r})}(\mathbf{x}) - \delta(f; \mathbf{q}, \mathbf{p})|.$$

Using [9], write the divided difference in integral form

$$\begin{aligned}
& \mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x}) \\
&\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \int_{R''} |f^{(\mathbf{r})}(\mathbf{x}) - f^{(\mathbf{r})}(\mathbf{x}^*)| \left( \prod_{i \in M} d\alpha_i \right), \quad (17)
\end{aligned}$$

where

$$R'' := [0, 1]^{|M|}$$

and

$$\mathbf{x}^* = (x_1^*, x_2^*, \dots, x_n^*), \quad \text{with } x_i^* = \begin{cases} x_i + \alpha_i(x_i^{j_i - l_i + 1} - x_i), & \text{if } i \in M \\ x_i^{j_i + l_i}, & \text{if } i \notin M \end{cases}.$$

## 5. Approximation of derivatives of functions by derivatives of splines

In this sections, we look at approximating a function's derivative by the derivative of the linear spline that is constructed to interpolate the function itself. The next two theorems correspond to the first two theorems if we only consider the original function.

In the following result, we estimate the error of approximation on the class  $C_D^{\mathbf{r}}(\Omega)$ , denoted by  $E_{\mathbf{m}}^{\mathbf{r}}(C_D^{\mathbf{r}}(\Omega))$ .

**Theorem 3.** *Let  $\mathbf{r} \in \{0, 1\}^n$  be given and  $M := \{i : r_i = 1\}$ . Let also an arbitrary function  $\Omega(\boldsymbol{\gamma})$  of MC-type, concave with respect to  $\gamma_i$ , where  $i \notin M$ , be given. Then for  $\mathbf{m} \in \mathbb{N}^n$  with  $m_i \geq 2$ ,  $i = 1, \dots, n$ , the error of approximation on the class  $C_D^{\mathbf{r}}(\Omega)$  is*

$$E_{\mathbf{m}}^{\mathbf{r}}(C_D^{\mathbf{r}}(\Omega)) = \left( \prod_{i \in M} m_i \right) \int_R \Omega(\mathbf{h}) \left( \prod_{i \in M} d\gamma_i \right),$$

where

$$\mathbf{h} = (h_1, h_2, \dots, h_n), \quad \text{with } h_i = \begin{cases} \gamma_i, & \text{if } i \in M \\ \frac{1}{2m_i}, & \text{if } i \notin M \end{cases}$$

and  $R = \prod_{i \in M} [0, \frac{1}{m_i}]$ .

### Proof

For any  $\mathbf{x}$  from an arbitrary  $D_{\mathbf{j}} := \prod_{i=1}^n [x_i^{j_i}, x_i^{j_i+1}]$  and for given  $f \in C_D^{\mathbf{r}}(\Omega)$  using the presentation of the divided difference in integral form (17) and Definition 4, we have

$$|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| \leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \int_{R''} \Omega(\boldsymbol{\beta}) \left( \prod_{i \in M} d\alpha_i \right), \quad (18)$$

where

$$\boldsymbol{\beta} = (\beta_1, \beta_2, \dots, \beta_n), \text{ with } \beta_i = \begin{cases} \alpha_i |x_i^{j_i - l_i + 1} - x_i|, & \text{if } i \in M \\ |x_i - x_i^{j_i + l_i}|, & \text{if } i \notin M \end{cases}.$$

By (18) and for  $\mathbf{x} \in D_j$  we have

$$|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| \leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \int_{R''} \Omega(\boldsymbol{\beta}^*) \left( \prod_{i \in M} d\alpha_i \right), \quad (19)$$

where

$$\boldsymbol{\beta}^* = (\beta_1^*, \beta_2^*, \dots, \beta_n^*), \text{ with } \beta_i^* = \begin{cases} \frac{\alpha_i}{m_i} H_{l_i, j_i}(x_i), & \text{if } i \in M \\ \frac{1}{m_i} H_{1-l_i, j_i}(x_i), & \text{if } i \notin M \end{cases}.$$

Taking into account that  $\Omega(\boldsymbol{\gamma})$  is concave with respect to  $\gamma_i$ ,  $i \notin M$ , and performing a change of variables, we obtain

$$|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| \leq \left( \prod_{i \in M} m_i \right) \sum_{l_{i_1}=0}^1 \dots \sum_{l_{i_{|M|}}=0}^1 \int_{R'} \Omega(\boldsymbol{\beta}') \left( \prod_{i \in M} d\gamma_i \right),$$

where  $i_k \in M$ ,  $R' := \prod_{i \in M} [0, m_i^{-1} H_{l_i, j_i}(x_i)]$ , and

$$\boldsymbol{\beta}' = (\beta'_1, \beta'_2, \dots, \beta'_n), \quad \text{with} \quad \beta'_i = \begin{cases} \gamma_i, & \text{if } i \in M \\ \frac{2}{m_i} H_{0, j_i}(x_i) H_{1, j_i}(x_i), & \text{if } i \notin M \end{cases}.$$

We have  $\frac{2}{m_i} H_{0, j_i}(x_i) H_{1, j_i}(x_i) = \lambda(x_i)$ , where  $\lambda(x_i)$  is defined in (8). Therefore, by (9) we have that  $\beta'_i \leq \beta''_i$  for all  $i = 1, \dots, n$ , where

$$\boldsymbol{\beta}'' = (\beta''_1, \beta''_2, \dots, \beta''_n), \quad \text{with} \quad \beta''_i = \begin{cases} \gamma_i, & \text{if } i \in M \\ \frac{1}{2m_i}, & \text{if } i \notin M \end{cases}. \quad (20)$$

The fact that  $\Omega(\boldsymbol{\gamma})$  is non-decreasing together with (20) imply

$$\begin{aligned} |\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| &\leq \left( \prod_{i \in M} m_i \right) \sum_{l_{i_1}=0}^1 \dots \sum_{l_{i_{|M|}}=0}^1 \int_{R'} \Omega(\boldsymbol{\beta}'') \left( \prod_{i \in M} d\gamma_i \right) \\ &= \Phi(\mathbf{x}). \end{aligned} \quad (21)$$



It is easy to verify that  $\Phi(\mathbf{x})$  is continuous on  $[x_i^{j_i}, x_i^{j_i+1}]$  for  $i \in M$ . As  $\Omega(\gamma) \geq 0$ , it is also easy to verify that

$$\max\{\Phi(\mathbf{x}) : x_i \in [x_i^{j_i}, x_i^{j_i+1}], i \in M\} = \Phi(\mathbf{x}^{j+1}), \mathbf{l} = (l_1, \dots, l_n), l_i = 0, 1. \quad (22)$$

By (21) and (22), we have

$$\begin{aligned} |\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| &\leq \Phi(\mathbf{x}^{\mathbf{j}}) \\ &= \left( \prod_{i \in M} m_i \right) \int_R \Omega(\beta'') \left( \prod_{i \in M} d\gamma_i \right), \end{aligned}$$

where  $R = \prod_{i \in M} [0, \frac{1}{m_i}]$ . Setting  $\beta'' = \mathbf{h}$  and using the fact that the last inequality holds for any function  $f \in C_D^{\mathbf{r}}(\Omega)$ , we have the upper bound

$$E_{\mathbf{m}}^{\mathbf{r}}(C_D^{\mathbf{r}}(\Omega)) \leq \left( \prod_{i \in M} m_i \right) \int_R \Omega(\mathbf{h}) \left( \prod_{i \in M} d\gamma_i \right). \quad (23)$$

In order to show that the upper bound (23) is achieved, we introduce the extremal function

$$d(\mathbf{x}) := \int_S \pi(\mathbf{h}') \left( \prod_{i \in M} d\gamma_i \right),$$

where  $S = \prod_{i \in M} [0, x_i]$ ,

$$\mathbf{h}' = (h'_1, h'_2, \dots, h'_n), \quad \text{with} \quad h'_i = \begin{cases} \gamma_i, & \text{if } i \in M \\ x_i, & \text{if } i \notin M \end{cases},$$

for  $\mathbf{x} \in \prod_{i \in M} [\frac{l_i}{m_i}, \frac{l_i+1}{m_i}] \times \prod_{i \notin M} [\frac{l_i}{2m_i}, \frac{l_i+1}{2m_i}]$ ,  $l_i = 0, 1$ ,  $i = 1, \dots, n$ ,

$$\pi(\mathbf{x}) = \Omega(\mathbf{h}'') - \left( \prod_{i \in M} m_i \right) \int_R \Omega(\mathbf{h}) \left( \prod_{i \in M} d\gamma_i \right),$$

where

$$\mathbf{h}'' = (h''_1, h''_2, \dots, h''_n), \quad \text{with} \quad h''_i = \begin{cases} (-1)^{l_i} \left( \frac{1}{m_i} - x_i \right), & \text{if } i \in M \\ (-1)^{l_i} \left( \frac{1}{2m_i} - x_i \right), & \text{if } i \notin M \end{cases}$$

and extend function  $\pi(\mathbf{x})$  to be  $\frac{2}{m_i}$ -periodic for  $x_i$  such that  $i \in M$ , and to be  $\frac{1}{m_i}$ -periodic for  $x_i$  where  $i \notin M$ .

From the way that  $d(\mathbf{x})$  is defined, we see that it is in the class  $C_D^{\mathbf{r}}(\Omega)$ . In addition, we have that  $d(\mathbf{x}^{\mathbf{j}}) = 0$  for  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i$ , so it follows that  $S_{\mathbf{m}}(d; \mathbf{x}) = 0$  as the spline is linear in each  $x_i$  on every element of the partition. With  $S_{\mathbf{m}}^{(\mathbf{r})}(d; \mathbf{x}) = 0$ , we obtain the following inequality

$$\begin{aligned} E_{\mathbf{m}}^{\mathbf{r}}(C_D^{\mathbf{r}}(\Omega)) &\geq \|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(d)\|_C = \|d^{(\mathbf{r})}\|_C \geq |d^{(\mathbf{r})}(\boldsymbol{\phi})| \\ &= \left( \prod_{i \in M} m_i \right) \int_R \Omega(\mathbf{h}) \left( \prod_{i \in M} d\gamma_i \right), \end{aligned} \quad (24)$$

where

$$\boldsymbol{\phi} = (\phi_1, \phi_2, \dots, \phi_n), \quad \text{with} \quad \phi_i = \begin{cases} \frac{1}{m_i}, & \text{if } i \in M \\ \frac{1}{2m_i}, & \text{if } i \notin M \end{cases}.$$

Comparing (23) and (24), we obtain the approximation error to be

$$E_{\mathbf{m}}^{\mathbf{r}}(C_D^{\mathbf{r}}(\Omega)) = \left( \prod_{i \in M} m_i \right) \int_R \Omega(\mathbf{h}) \left( \prod_{i \in M} d\gamma_i \right). \quad \square$$

Theorem 4 provides the estimate for the error of approximation on the class  $C_{D,p}^{\mathbf{r}}(\Omega)$ .

**Theorem 4.** *Let  $\mathbf{r} \in \{0, 1\}^n$  be given and let  $M = \{i : r_i = 1\}$ . Let also an arbitrary univariate, concave, MC-type function  $\Omega(\gamma)$  be given. Then for  $\mathbf{m} \in \mathbb{N}^n$  with  $m_i \geq 2$ ,  $i = 1, \dots, n$ , the error of approximation on the class  $C_{D,p}^{\mathbf{r}}(\Omega)$ ,  $1 \leq p \leq 3$ , is*

$$E_{\mathbf{m}}^{\mathbf{r}}(C_{D,p}^{\mathbf{r}}(\Omega)) = \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right),$$

where  $R = \prod_{i \in M} [0, \frac{1}{m_i}]$ .

**Proof**

Let arbitrary  $f \in C_D^{\mathbf{r}}(\Omega)$  be given. For any  $\mathbf{x}$  from an arbitrary  $D_{\mathbf{j}} :=$

$\prod_{i=1}^n [x_i^{j_i}, x_i^{j_i+1}]$ , using the estimate of the error in the form (17), and using Definitions 3 of  $\Omega(\gamma)$  and Definition 5 of the class  $C_D^r(\Omega)$ , we have

$$\begin{aligned}
|\mathcal{E}_{\mathbf{m}}^r(f; \mathbf{x})| &\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \\
&\times \int_{R''} \omega_p \left( f^{(\mathbf{r})}; \sqrt[p]{\sum_{i \in M} [\alpha_i |x_i^{j_i - l_i + 1} - x_i|]^p + \sum_{i \notin M} |x_i - x_i^{j_i + l_i}|^p} \right) \left( \prod_{i \in M} d\alpha_i \right) \\
&\leq \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i=1}^n H_{l_i, j_i}(x_i) \right) \\
&\times \int_{R''} \Omega \left( \sqrt[p]{\sum_{i \in M} \left( \frac{\alpha_i}{m_i} H_{l_i, j_i} \right)^p + \sum_{i \notin M} \left( \frac{1}{m_i} H_{1-l_i, j_i} \right)^p} \right) \left( \prod_{i \in M} d\alpha_i \right),
\end{aligned}$$

where  $R'' := [0, 1]^{|M|}$ .

Performing the change of variables, taking into account that  $\Omega(\gamma)$  is concave, and using notation  $R' := \prod_{i \in M} [0, m_i^{-1} H_{l_i, j_i}(x_i)]$ , we have

$$\begin{aligned}
|\mathcal{E}_{\mathbf{m}}^r(f; \mathbf{x})| &\leq \left( \prod_{i \in M} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_n=0}^1 \left( \prod_{i \notin M} H_{l_i, j_i}(x_i) \right) \\
&\times \int_{R'} \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \left( \frac{1}{m_i} H_{1-l_i, j_i} \right)^p \right]} \right) \left( \prod_{i \in M} d\gamma_i \right) \\
&\leq \left( \prod_{i \in M} m_i \right) \sum_{l_1=0}^1 \dots \sum_{l_{|M|}=0}^1 \\
&\times \int_{R'} \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \alpha^p(x_i) \right]} \right) \left( \prod_{i \in M} d\gamma_i \right),
\end{aligned}$$

where  $i_k \in M$  and  $\alpha(x_i)$  is defined in (12).

Recall that in Theorem 2 we have proved that for any  $\mathbf{x} \in D_j$

$$\alpha(x_i) \leq \frac{1}{(2m_i)^p}, \quad i = 1, \dots, n.$$

Therefore, since  $\Omega(\gamma)$  is non-decreasing, we have

$$\begin{aligned}
|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(f; \mathbf{x})| &\leq \left( \prod_{i \in M} m_i \right) \sum_{l_{i_1}=0}^1 \dots \sum_{l_{i_{|M|}}=0}^1 \\
&\times \int_{R'} \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right) \\
&= \mu(\mathbf{x}).
\end{aligned} \tag{25}$$

It is easy to verify that

$$\begin{aligned}
&\max\{\mu(\mathbf{x}) : \mathbf{x} \in D_{\mathbf{j}}\} \\
&= \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right), \tag{26}
\end{aligned}$$

where  $R = [0, \frac{1}{m_i}]^{|M|}$  for  $i \in M$ . Therefore, using (26) and the fact that (25) holds true for any  $f \in C_{D,p}^{\mathbf{r}}(\Omega)$ , we have

$$E_{\mathbf{m}}^{\mathbf{r}}(C_{D,p}^{\mathbf{r}}(\Omega)) \leq \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\sum_{i \in M} \gamma_i^p + \sum_{i \notin M} \frac{1}{(2m_i)^p}} \right) \left( \prod_{i \in M} d\gamma_i \right). \tag{27}$$

In order to show that equality in (27) is achieved, we introduce the extremal function

$$e(\mathbf{x}) := \int_S \pi(\mathbf{h}') \left( \prod_{i \in M} d\gamma_i \right)$$

where  $S = [0, x_i]^{|M|}$  for  $i \in M$ ,

$$\mathbf{h}' = (h'_1, h'_2, \dots, h'_n), \quad \text{with} \quad h'_i = \begin{cases} \gamma_i, & \text{if } i \in M \\ x_i, & \text{if } i \notin M \end{cases},$$

and function  $\pi(\mathbf{x})$  is defined as

$$\begin{aligned} \pi(\mathbf{x}) &= \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \left( (-1)^{l_i} \left( \frac{1}{m_i} - x_i \right) \right)^p \right] + \left[ \sum_{i \notin M} \left( (-1)^{l_i} \left( \frac{1}{2m_i} - x_i \right) \right)^p \right]} \right) \\ &\quad - \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right) \end{aligned}$$

for  $\mathbf{x} \in \prod_{i \in M} [\frac{l_i}{m_i}, \frac{l_i+1}{m_i}] \times \prod_{i \notin M} [\frac{l_i}{2m_i}, \frac{l_i+1}{2m_i}]$ ,  $l_i = 0, 1$ ,  $i = 1, \dots, n$  and then extended so that  $\pi(\mathbf{x})$  is  $\frac{2}{m_i}$ -periodic for  $x_i$  such that  $i \in M$  and is  $\frac{1}{m_i}$ -periodic for  $x_i$  where  $i \notin M$ .

From the way  $e(\mathbf{x})$  is defined, we see that it clearly belongs to the class  $C_D^{\mathbf{r}}(\Omega)$ . We have that  $e(\mathbf{x}^{\mathbf{j}}) = 0$  for  $\mathbf{j} = (j_1, \dots, j_n)$ ,  $j_i = 0, \dots, m_i$ , so it follows that  $S_{\mathbf{m}}(e; \mathbf{x}) = 0$  as the spline is linear in each  $x_i$  on each partition element. With  $S_{\mathbf{m}}^{\mathbf{r}}(e; \mathbf{x}) = 0$ , we obtain the following inequality

$$\begin{aligned} E_{\mathbf{m}}^{\mathbf{r}}(C_{D,p}^{\mathbf{r}}(\Omega)) &\geq \|\mathcal{E}_{\mathbf{m}}^{\mathbf{r}}(e)\|_C = \|e^{(\mathbf{r})}\|_C \geq |e^{(\mathbf{r})}(\phi)| \\ &= \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right), \quad (28) \end{aligned}$$

where

$$\phi = (\phi_1, \phi_2, \dots, \phi_n), \quad \text{with } \phi_i = \begin{cases} \frac{1}{m_i}, & \text{if } i \in M \\ \frac{1}{2m_i}, & \text{if } i \notin M \end{cases}.$$

Comparing (27) and (28), we obtain the following error of approximation

$$\begin{aligned} E_{\mathbf{m}}^{\mathbf{r}}(C_{D,\rho_p}^{\mathbf{r}}(\Omega)) &= \left( \prod_{i \in M} m_i \right) \int_R \Omega \left( \sqrt[p]{\left[ \sum_{i \in M} \gamma_i^p \right] + \left[ \sum_{i \notin M} \frac{1}{(2m_i)^p} \right]} \right) \left( \prod_{i \in M} d\gamma_i \right). \quad \square \end{aligned}$$

**Remark.** If in the statement of the theorem all coordinates of the vector  $\mathbf{r}$  are equal to 1, then the assumption on  $\Omega(\gamma)$  to be concave can be removed.

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